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robots—that are capable of replacing human labor in a range of tasks. Industrial robots are argued to have already deeply impacted the labor market and are expected to transform it in the decades to come (e.g., Brynjolfsson and McAfee, 2012; Ford, 2016). Indeed, between 1993 and 2007 the stock of robots in the United States and Western

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the robot trajectory and the map building are performed once the measurements have been collected. Set-membership methods have often been considered for the localization of robots (see, e.g., [11] and [22] if the problem is linear, and also [1] when the robot is underwater). In situations where strong nonlinearities are involved, interval analysis

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